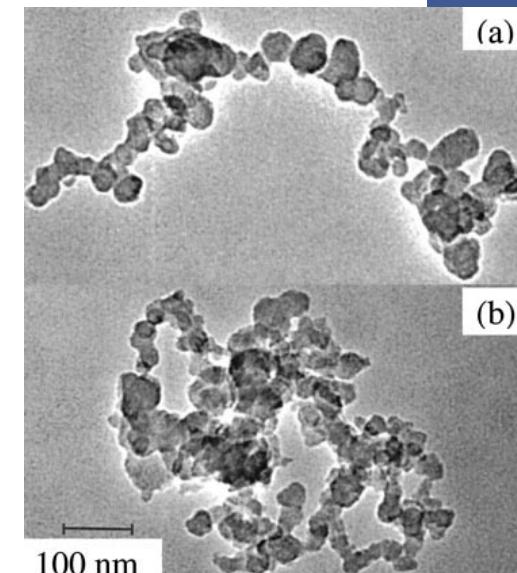
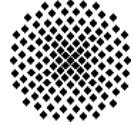


# Agglomeration of nano- and micron-sized particles



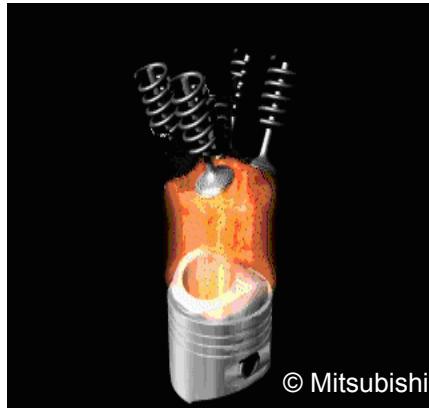
Prof. Andreas Kronenburg

Acknowledgements: G. Inci (ITV), R. Weeber (ICP), A. Arnold (ICP)

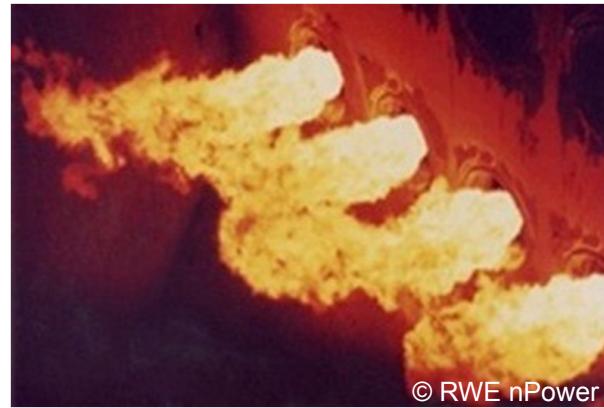


# Combustion Technology

- **Importance**
  - Combustion is everywhere



Vehicle Propulsion

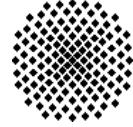


Energy Engg / Renewable Energies



Aerospace Engineering

- **Vision**
  - Efficient
  - clean
  - safe
- **Motivation - legislation**
  - Euro VI
  - “VISION 2020”



# Moving away from energy conversion ...

## Materials science, environmental engineering

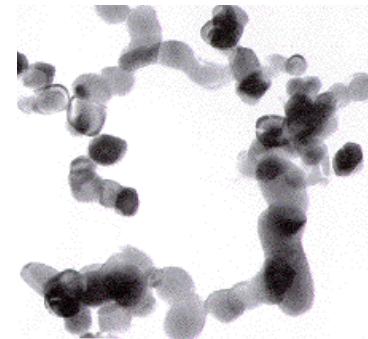
### 1. example: particle synthesis



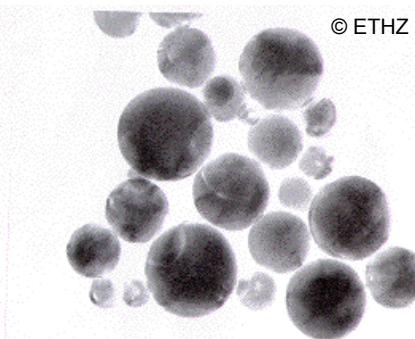
soot



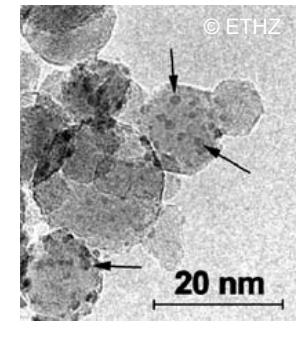
© ETHZ



Titania

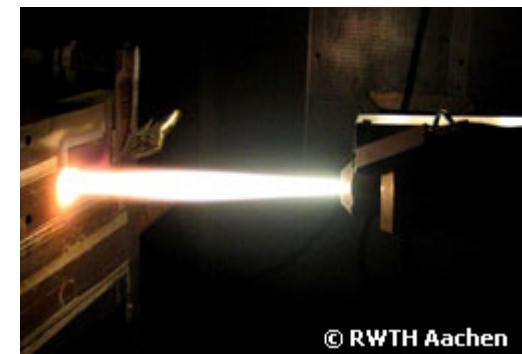
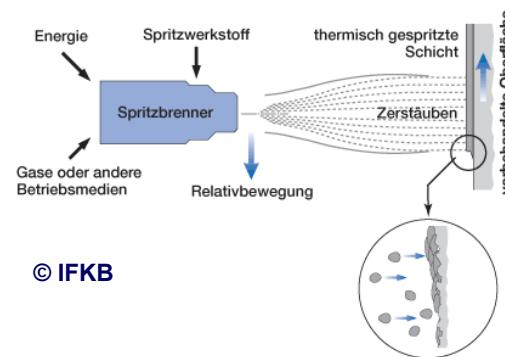


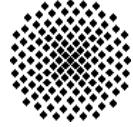
© ETHZ



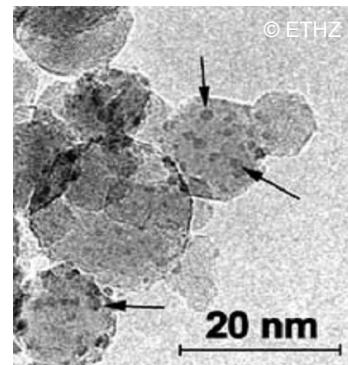
PT/TiO<sub>2</sub>

### 2. example: thermal coating





- **High temperature (flame) synthesis of nanoparticles constitutes 90% of particle production by mass and value**

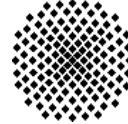


Pt/TiO<sub>2</sub> - particle



titanium dioxide

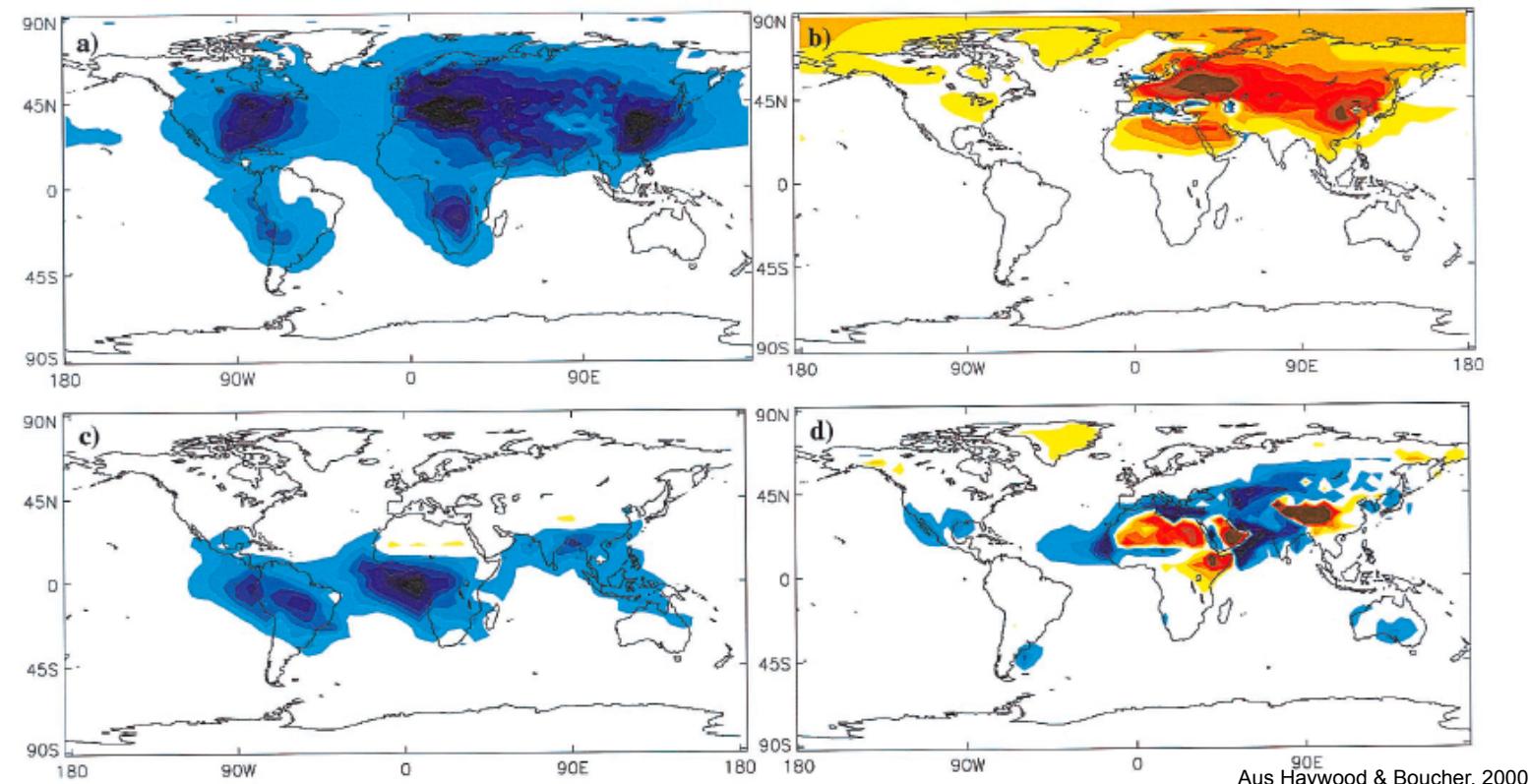
- **BUT: reactor design largely empirical, no models exist**
- **WHY? Estimated computational time is  $10^7$  years on Earth Simulator due to scale separation, nanometer vs. meters.**

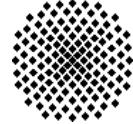


## Effects on climate

**Most important direct radiative forcing effect through sulfur**

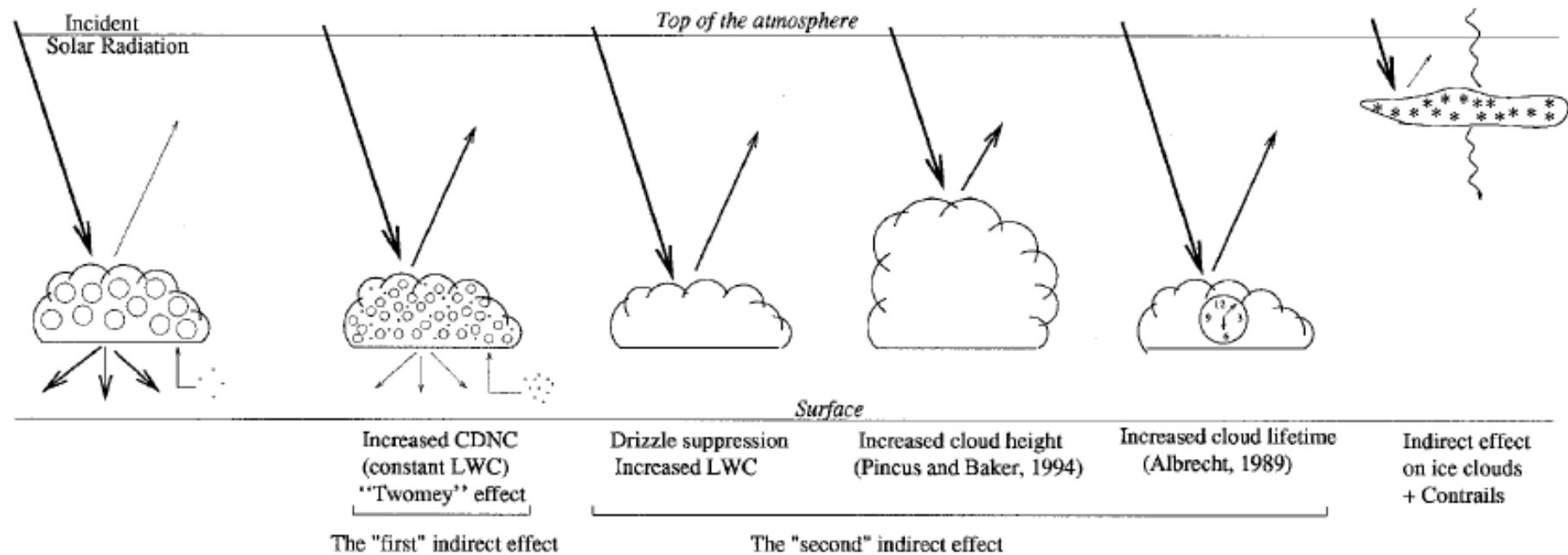
- Sulfataerosole:  $-0.8 \text{ W/m}^2$  to  $-0.20 \text{ W/m}^2$
- Black Carbon (fossil fuels):  $+0.03 \text{ W/m}^2$  to  $+0.30 \text{ W/m}^2$
- biomass:  $-0.6 \text{ W/m}^2$  to  $-0.07 \text{ W/m}^2$



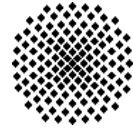


## SO<sub>3</sub> or sulfates are condensation kernels

→ secondary effects (change of microphysical (radiative) properties and of life cycle of clouds)

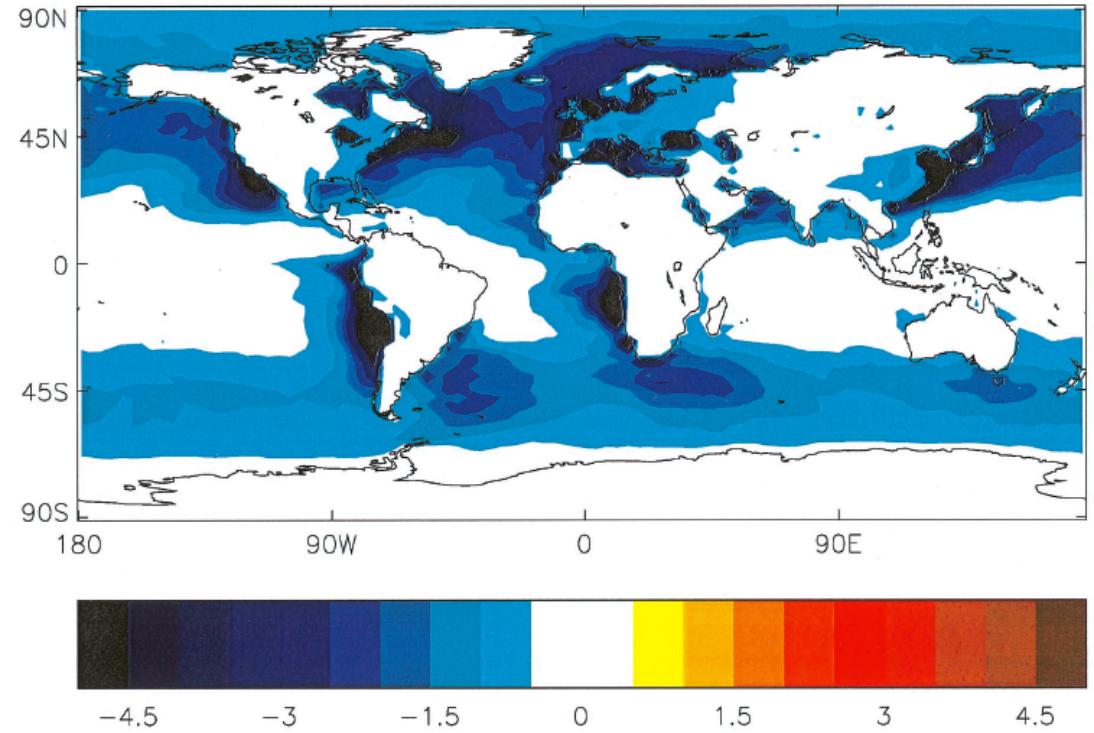
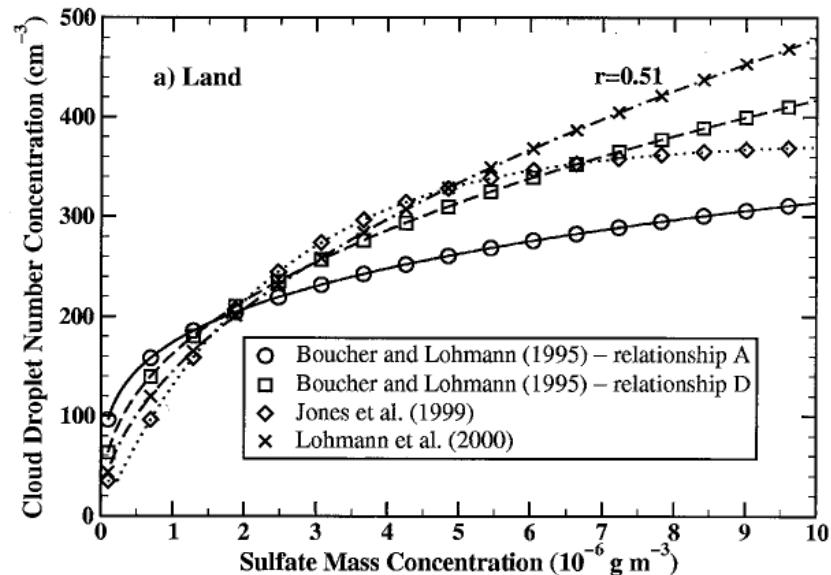


**Figure 1.** Schematic of the aerosol indirect effects. CDNC means cloud droplet number concentration, and LWC means liquid water content (aus Haywood & Boucher, 2000).

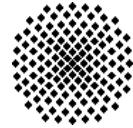


## ▪ indirect radiative forcing

- Albedo effect between  $-0.3 \text{ W/m}^2$  to  $-1.8 \text{ W/m}^2$

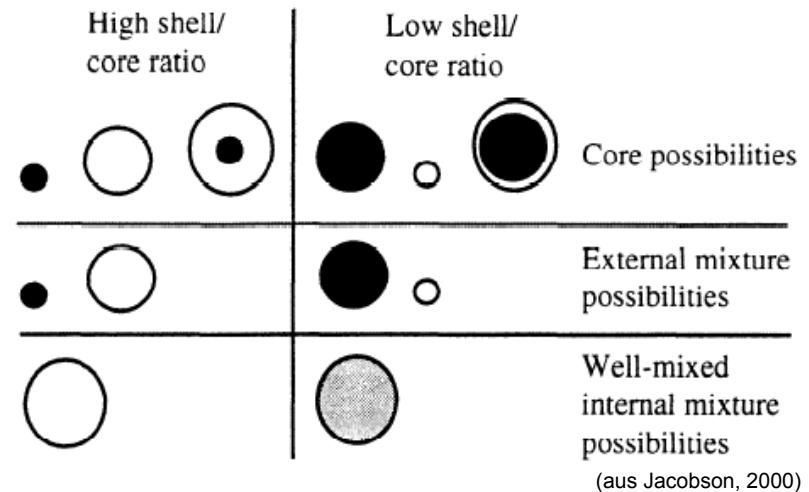
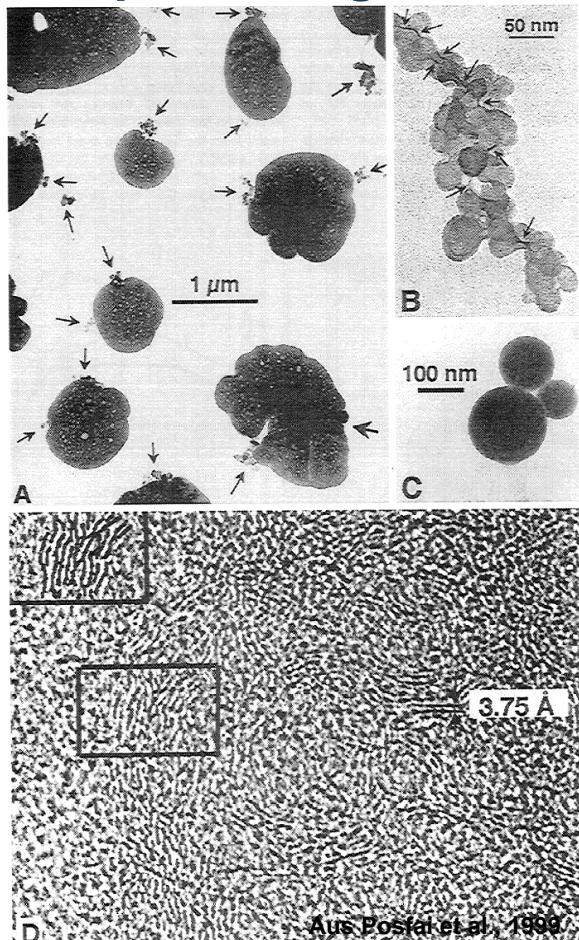


Aus Haywood & Boucher, 2000



Based on computations – predictions extremely difficult

### Example mixing: Sulfates and soot

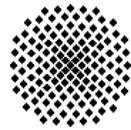


**Model:** external 50% higher than „core“-model  
well-mixed 40% lower than „core“

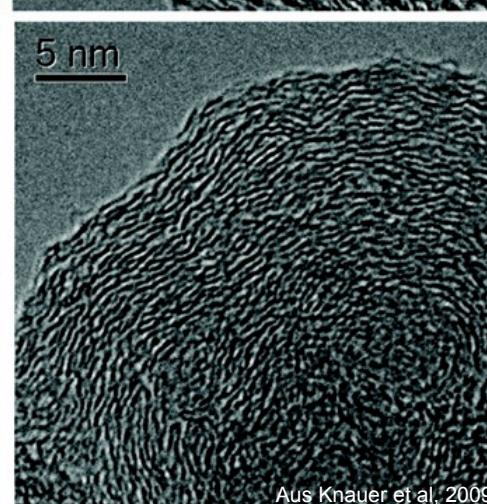
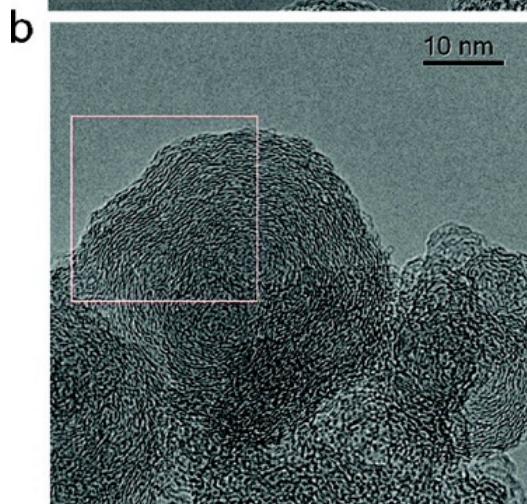
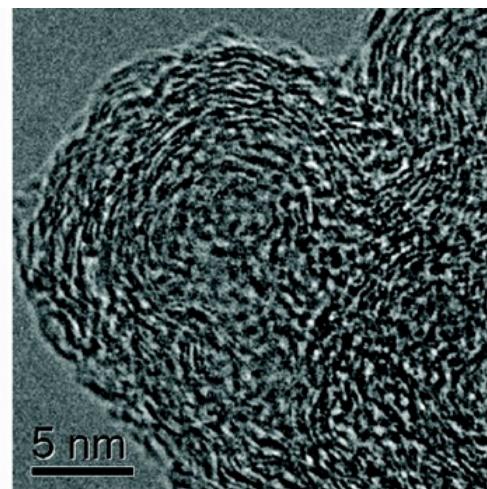
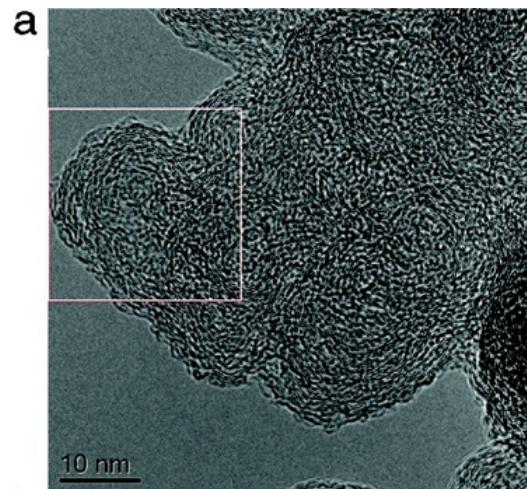
#### Radiative forcing:

Sulfate	-0.8 W/m <sup>2</sup> to -0.2 W/m <sup>2</sup>
Carbon	+0.2(well mixed) to +0.36 (internally mixed)

Internal mixing soot/sulfate: every percent of soot  
→ radiative forcing +0.034 W/m<sup>2</sup>

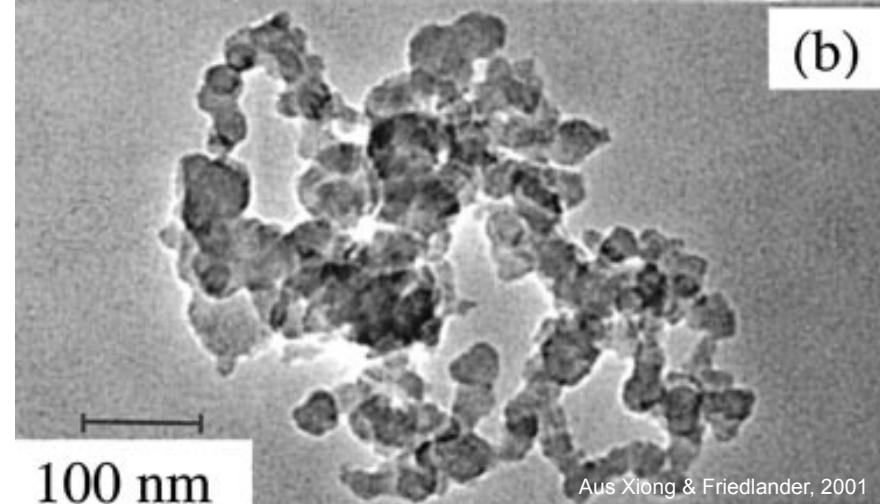
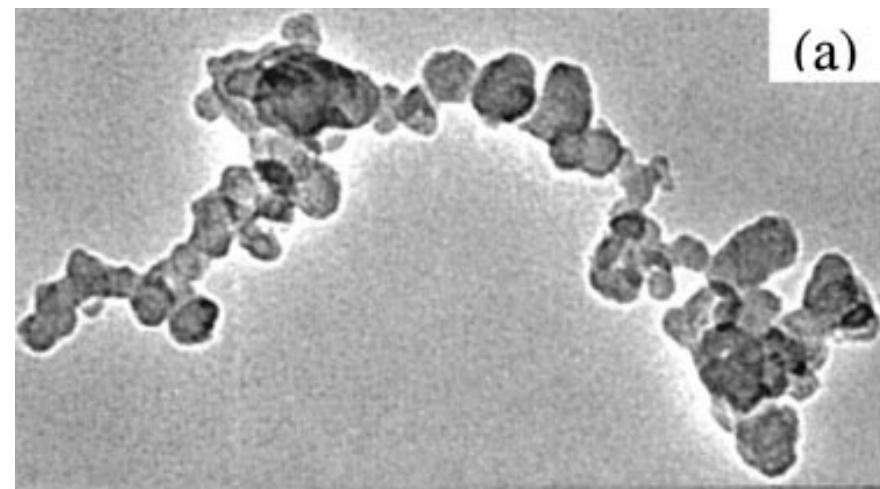


## structure:

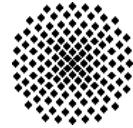


Aus Knauer et al., 2009

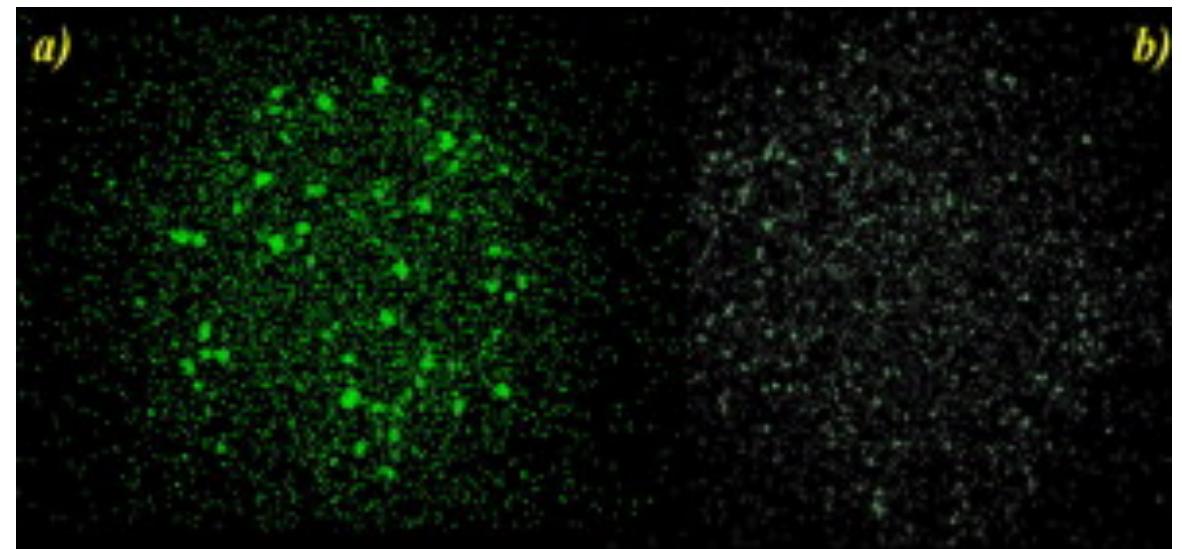
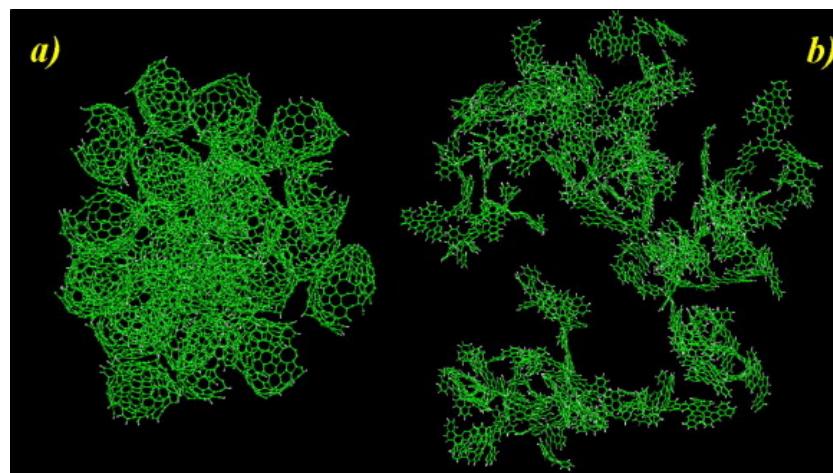
## Agglomeration:



Aus Xiong & Friedlander, 2001



## How can the structure be modelled?

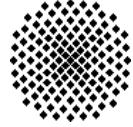


Agglomeration of flat ( $C_{202}H_{90}$ ) and spherical ( $C_{188}H_{53}$ ) particles with “coarse grained” simulationen  
(© A. Violi & S. Izvekov, 2007)



we do not want to go into that much detail

assume “microscopic” soot particles ( $\sim 10\text{-}100\text{ nm}$ )

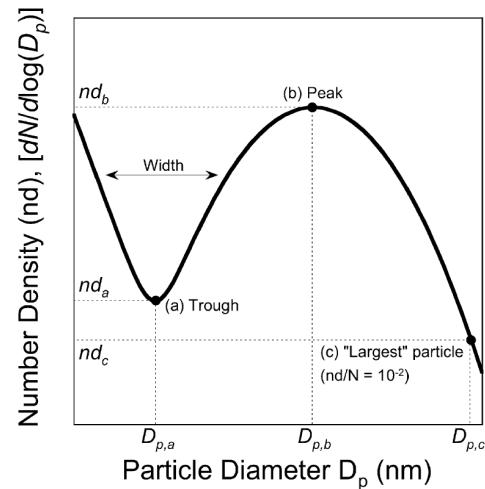


## Modelling of agglomeration in turbulent flow:

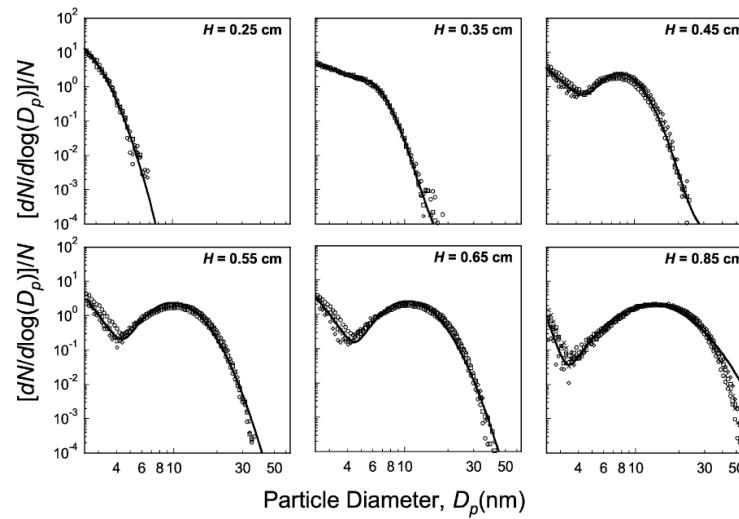
### Evolution of particle number density n (PBE or GDE):

$$\frac{\partial n}{\partial t} + \nabla \cdot n \mathbf{u} - \nabla \cdot D \nabla n + \frac{\partial G(v, \mathbf{Y}) n(v)}{\partial v} = S(v, \mathbf{Y}) + \frac{1}{2} \int_0^v \beta(\tilde{v}, v - \tilde{v}) n(\tilde{v}) n(v - \tilde{v}) d\tilde{v} - \int_0^v \beta(v, \tilde{v}) n(v) n(\tilde{v}) d\tilde{v}$$

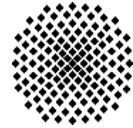
The particle number density is a function of (v, x, t) – v: particle volume



Typical PSD (Singh et al, 2006) for soot



PSD evolution (A.D. Abid, 2008) for soot



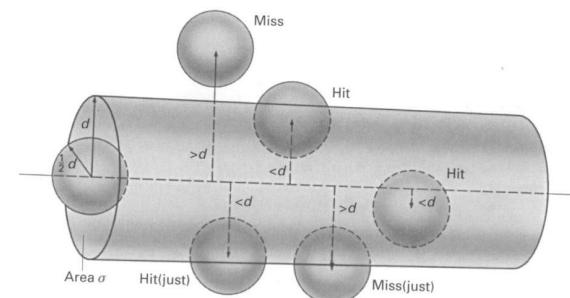
## Focus on aggregation

What is  $\beta(v_i, v_j)$ ?

collision kernel or collision frequency

How can it be modelled?

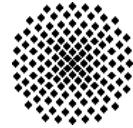
Free molecule range:



$$\longrightarrow \beta(v_i, v_j) = \pi(d_{pi} + d_{pj})^2 [k_B T / (\pi m_R)]^{1/2}$$

Continuum regime:

$$\longrightarrow \beta(v_i, v_j) = 4\pi(d_{pi} + d_{pj}) [D_i + D_j] \quad -D = \text{diffusion coefficient}$$



## Laminar shear and turbulence:

**Laminar shear:**

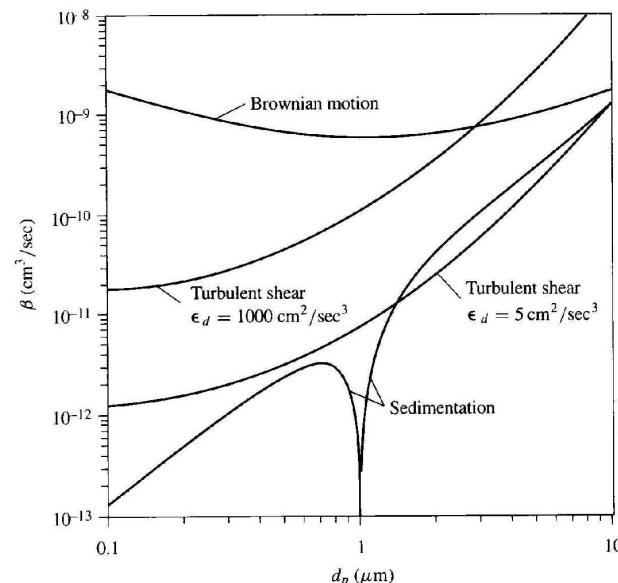
$$\beta(v_i, v_j) = \frac{4}{3} (v_i^{1/3} + v_j^{1/3})^3 \frac{du}{dx}$$

**Turbulence:**      **shear**

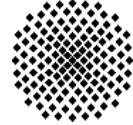
$$\beta(v_i, v_j) = 1.3 \left( \frac{\epsilon_d}{\nu} \right)^{1/2} (v_i^{1/3} + v_j^{1/3})^3 \quad \text{Saffman Turner limit}$$

**inertial coag**       $\beta(v_i, v_j) = 5.7 (v_i^{1/3} + v_j^{1/3})^2 \left| \frac{1}{\beta_i} - \frac{1}{\beta_j} \right| \frac{\epsilon_d^{3/4}}{\nu^{1/4}}$

## Comparison:

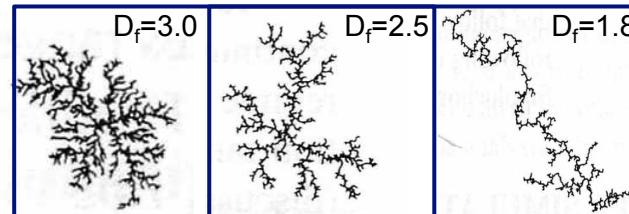


© Friedlander, 2000

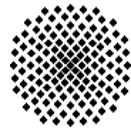


## Are the particles always spherical?

agglomeration due to turbulence vs. Brownian motion

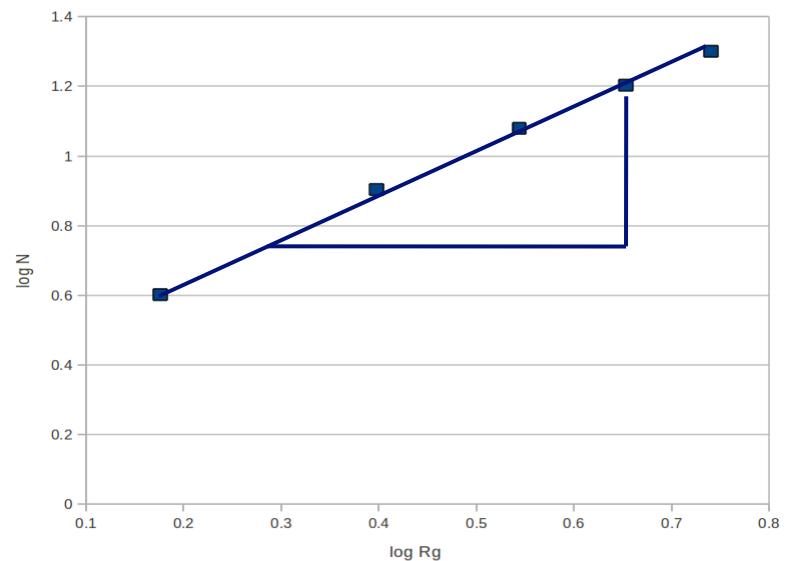
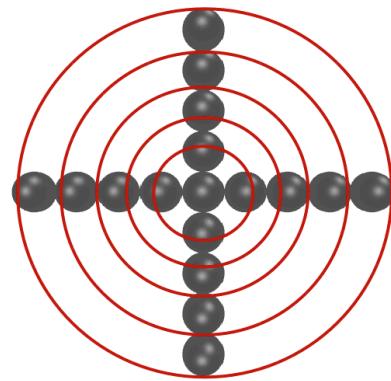


Fractal dimensions during particle agglomeration: agglomeration of primary particles due to convection (e.g. turbulence) (a), and agglomeration of primary particles (b) and of clusters (c) due to Brownian motion (adapted from DW Schaefer, 1988).



## Fractal Dimension

$$\log n_p = \log a + D_f \log R_g - D_f \log d_p$$

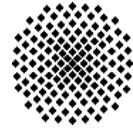


**Free molecule range:**

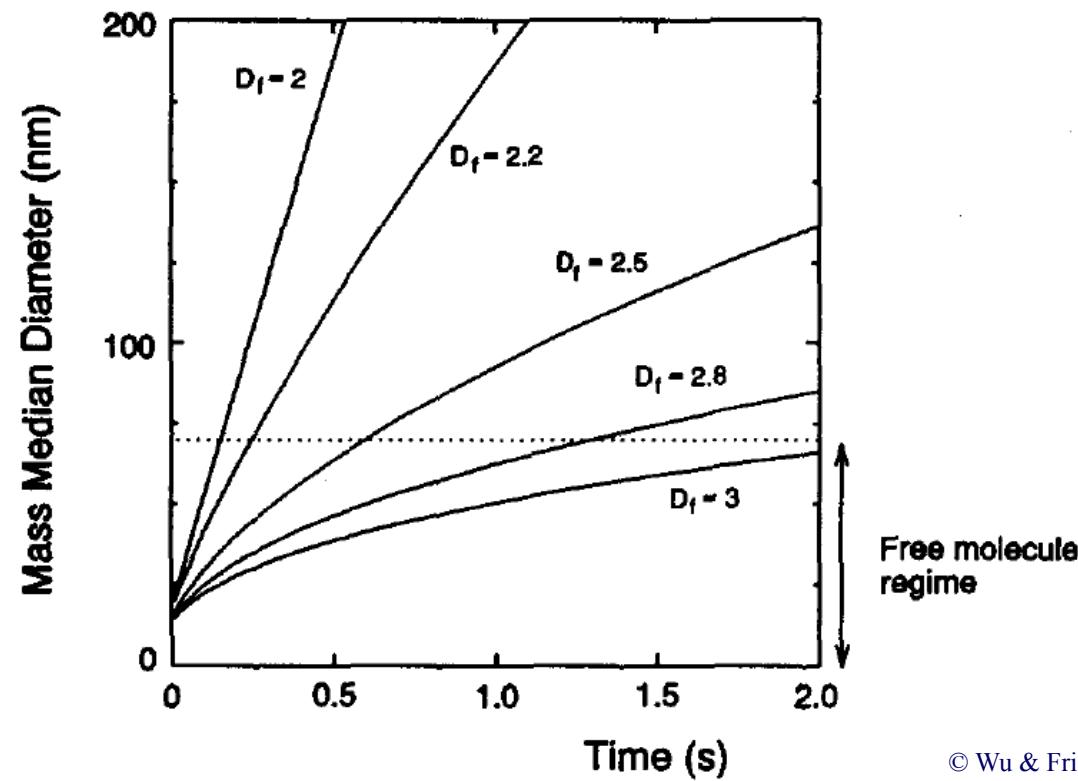
$$\longrightarrow \beta(v_i, v_j) = \left( \frac{6k_b T}{\rho} \right)^{1/2} \left( \frac{3}{4\pi} \right)^{2/D_f - 1/2} d_{p0}^{2-6/D_f} \left( \frac{1}{v_i} + \frac{1}{v_j} \right)^{1/2} (v_i^{1/D_f} + v_j^{1/D_f})^2$$

**Continuum regime:**

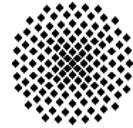
$$\longrightarrow \beta(v_i, v_j) = \frac{2k_b T}{3\mu} \left( \frac{1}{v_i^{1/D_f}} + \frac{1}{v_j^{1/D_f}} \right) (v_i^{1/D_f} + v_j^{1/D_f})^2$$



## Influence of fractal dimension on diameter:



© Wu & Friedlander, 1993



## HOW TO GET $D_f$ ?

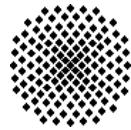
### ESPResSo

The motion and dynamics of the Brownian particles are modelled by solving the Langevin Equations of motion

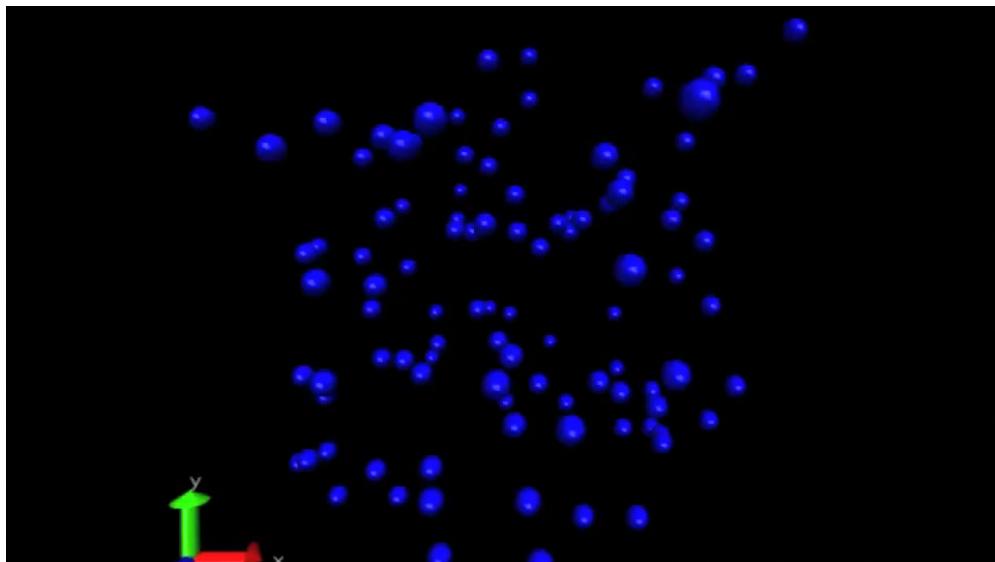
$$m_P \ddot{\mathbf{x}}_i = F_D + F_{ext} + BdW \quad (M \frac{du}{dt} + \gamma u = F(t))$$
$$\dot{\mathbf{x}} = \mathbf{v}(t, x)$$

### How to model particle collision and sticking?

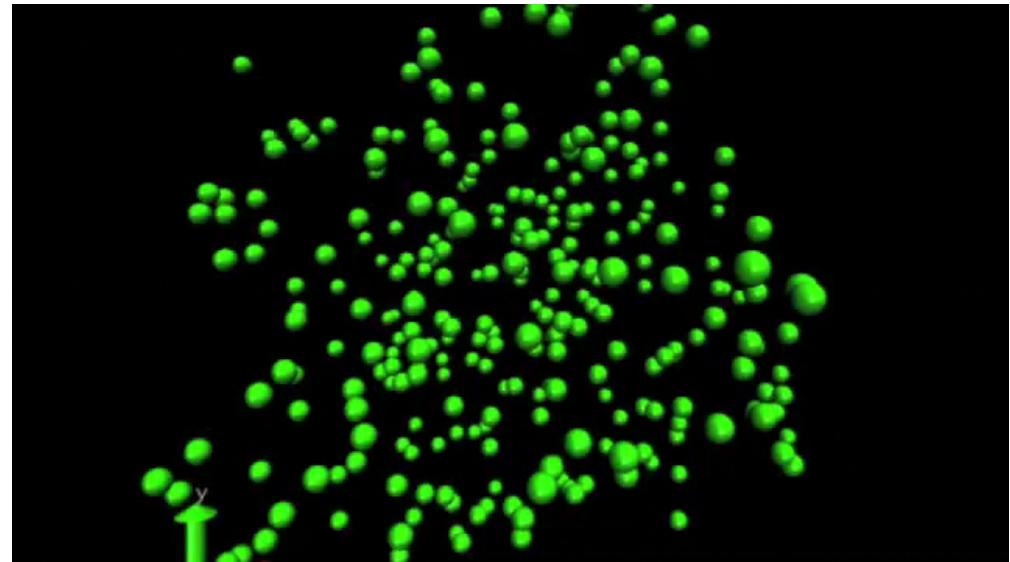
1. highly attractive LJ force
2. connect colliding particles to each other with a single bond
3. connection of 2 contacting particles with a single bond, 3<sup>rd</sup> particle with angle potential and 4<sup>th</sup> particle with dihedral potential



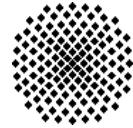
## Agglomeration of primary particles



LJ potential only



Single bond + angle + dihedral potentials



## 1. Highly attractive LJ force

- Due to attractive forces aggregates get compact

## 2. Connect colliding particles to each other with a single bond

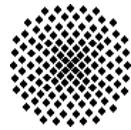
- Due to the spherically symmetric property and elastic property of bonds the connected particles have relative motion to each other

## 3. Single bond + angle potential + dihedral potential

- Cause a rapid energy increase in the system and result in bond broken problem

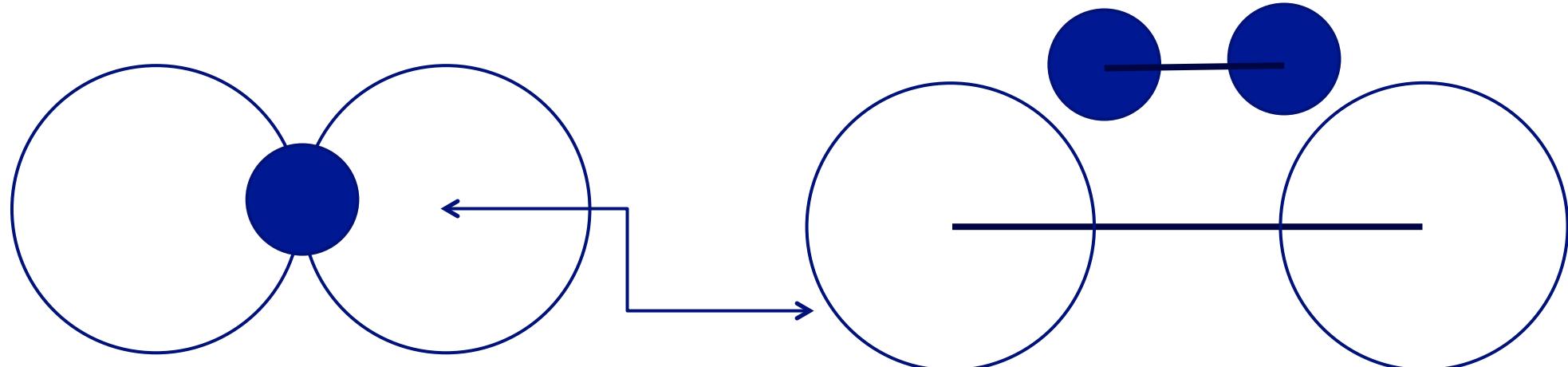
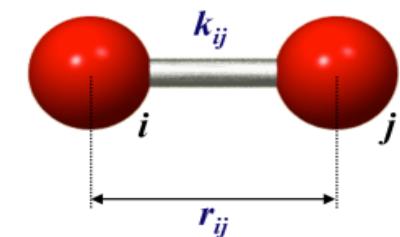
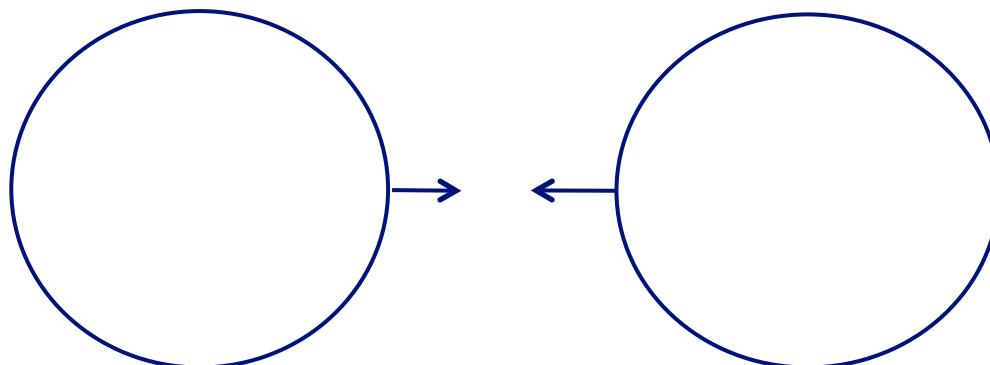


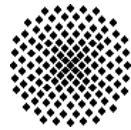
We need something else



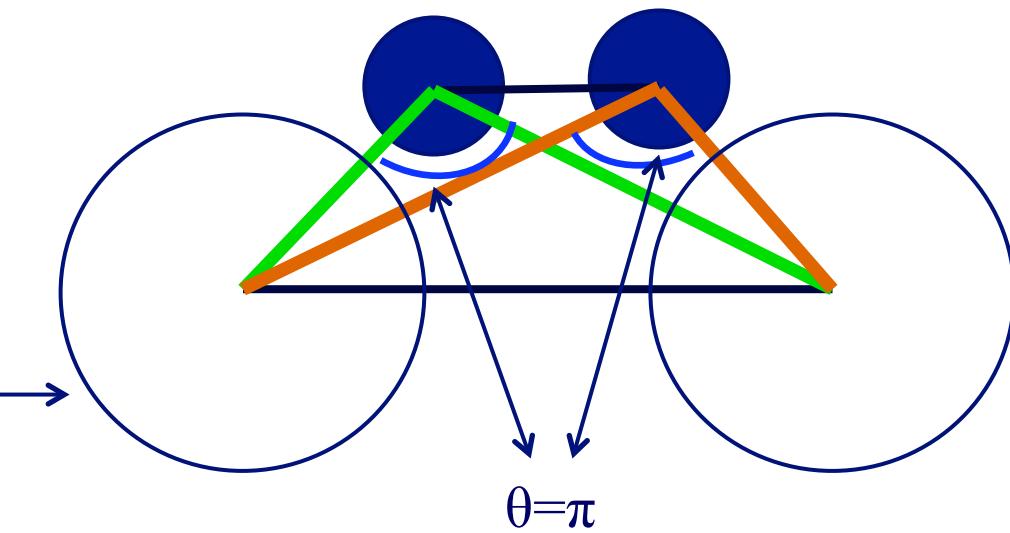
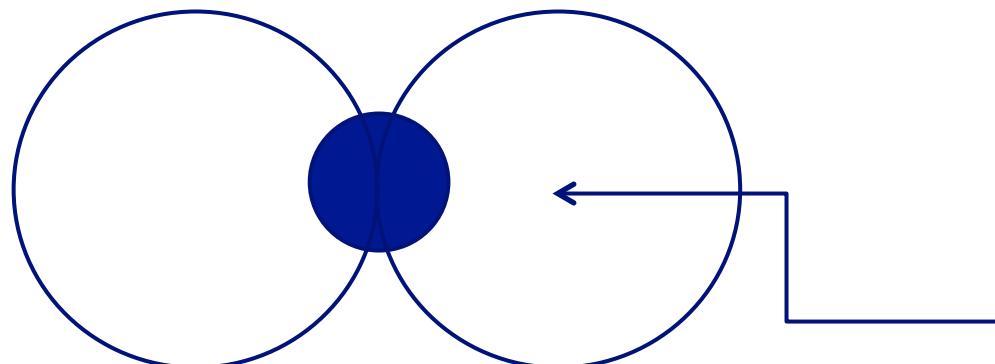
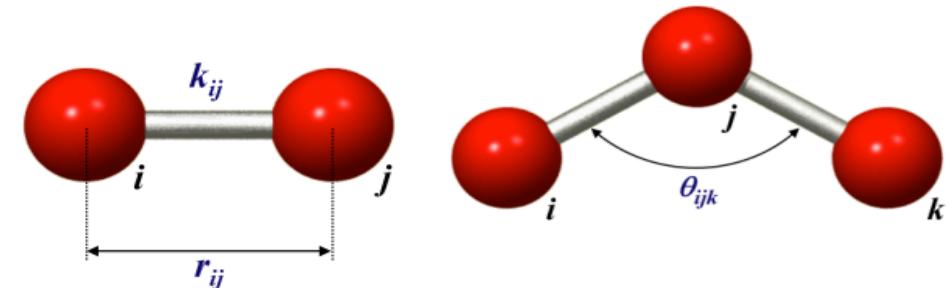
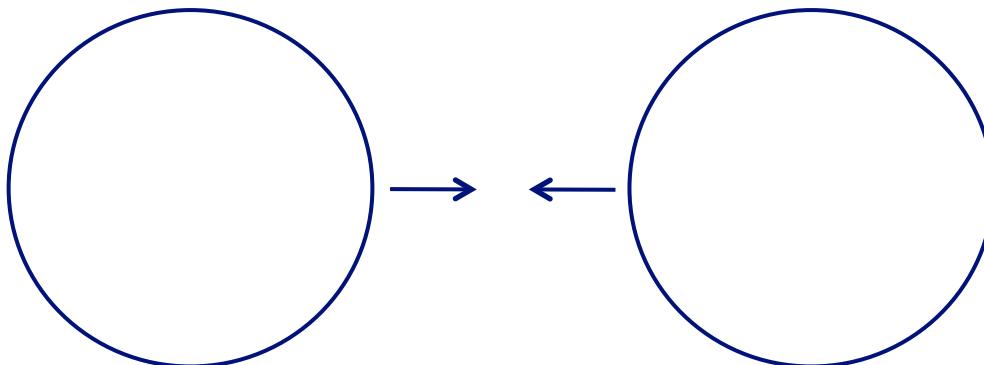
# Single Bonded Virtual Particles Model

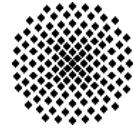
To avoid sliding motion - introduce virtual particles





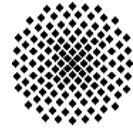
# Angle Bonded Virtual Particles Model





# Developed Models

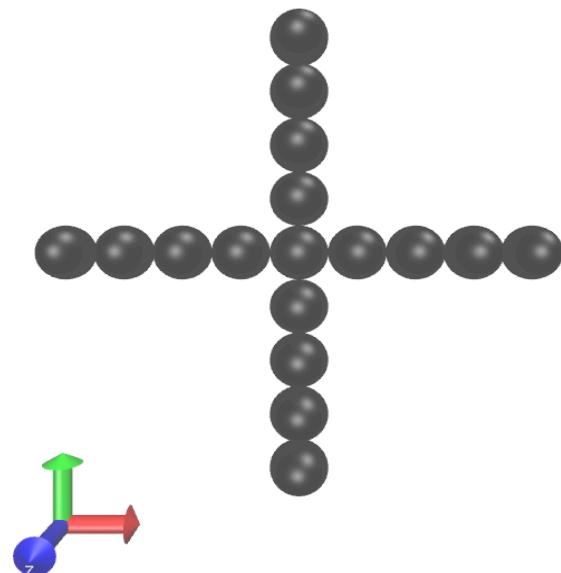
<b><i>Model Name</i></b>	<b><i>Model Description</i></b>	<b><i>Acronym</i></b>
<b>Model using highly attractive Lennard Jones potential</b>	<b>Collision model with highly attractive Lennard Jones potential</b>	<b>LJ</b>
<b>Single bond model</b>	<b>2-body potential between collided particles</b>	<b>SB</b>
<b>All bonds model</b>	<b>2-body, 3-body and 4-body potential between particles</b>	<b>AB</b>
<b>Single bonded virtual particles model</b>	<b>Collision model with two virtual particles at the collision point and connected by a 2-body potential</b>	<b>SBV</b>
<b>Angle bonded virtual particles model</b>	<b>Collision model with two virtual particles connected through 3-body potential</b>	<b>AnBV</b>



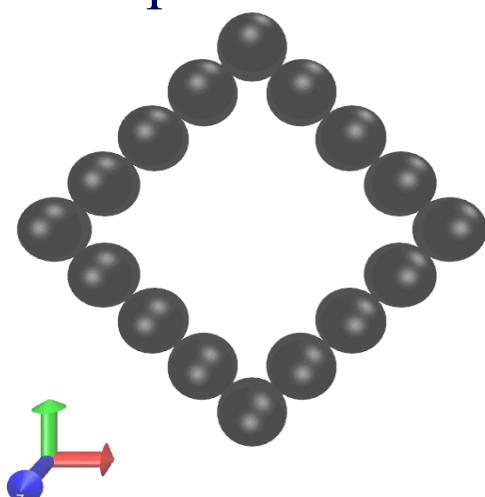
# MD Simulations – Test Cases

Pre-defined agglomerates

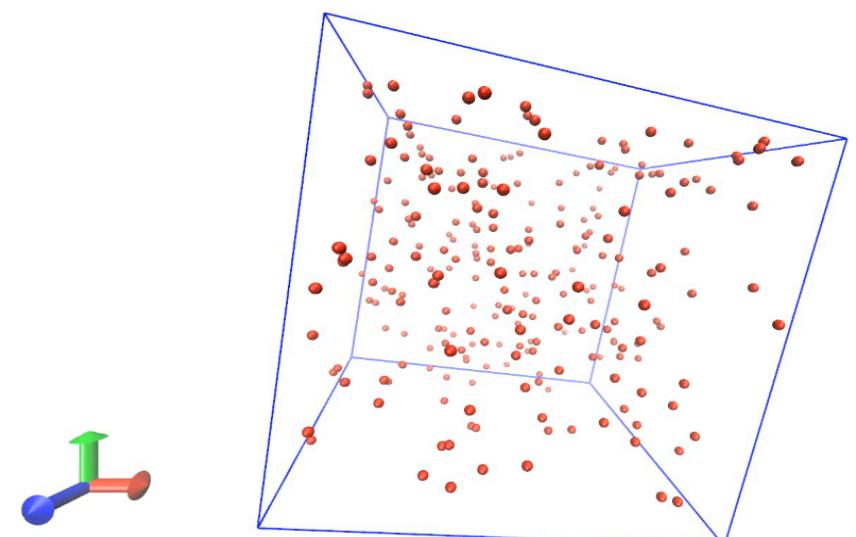
Cross-Shape

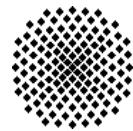


Square-  
Shape

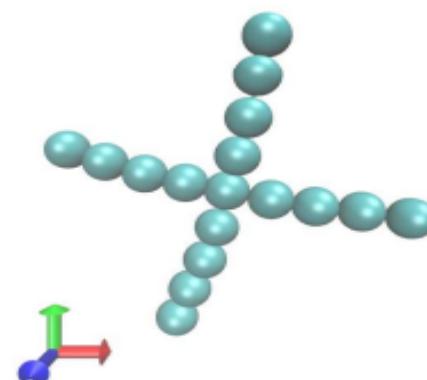
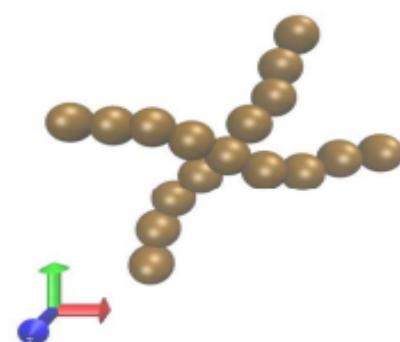
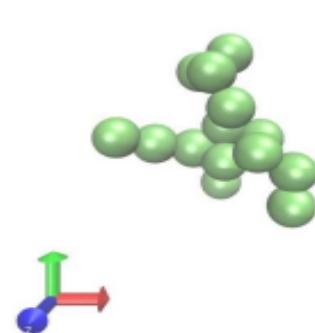
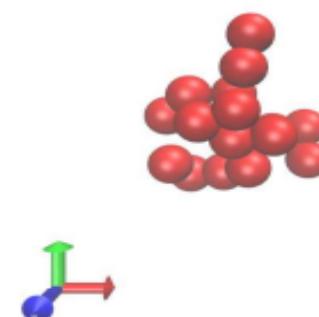
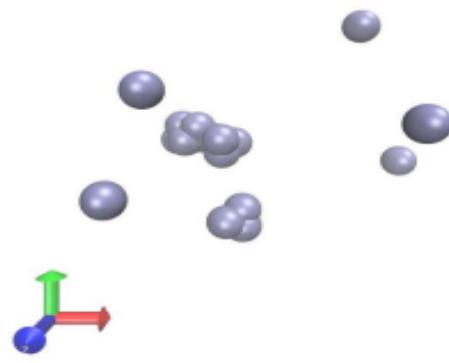
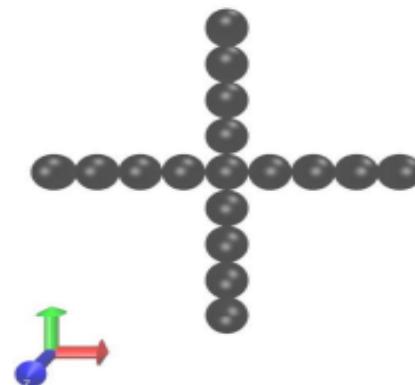


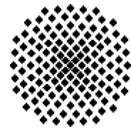
Randomly placed particles



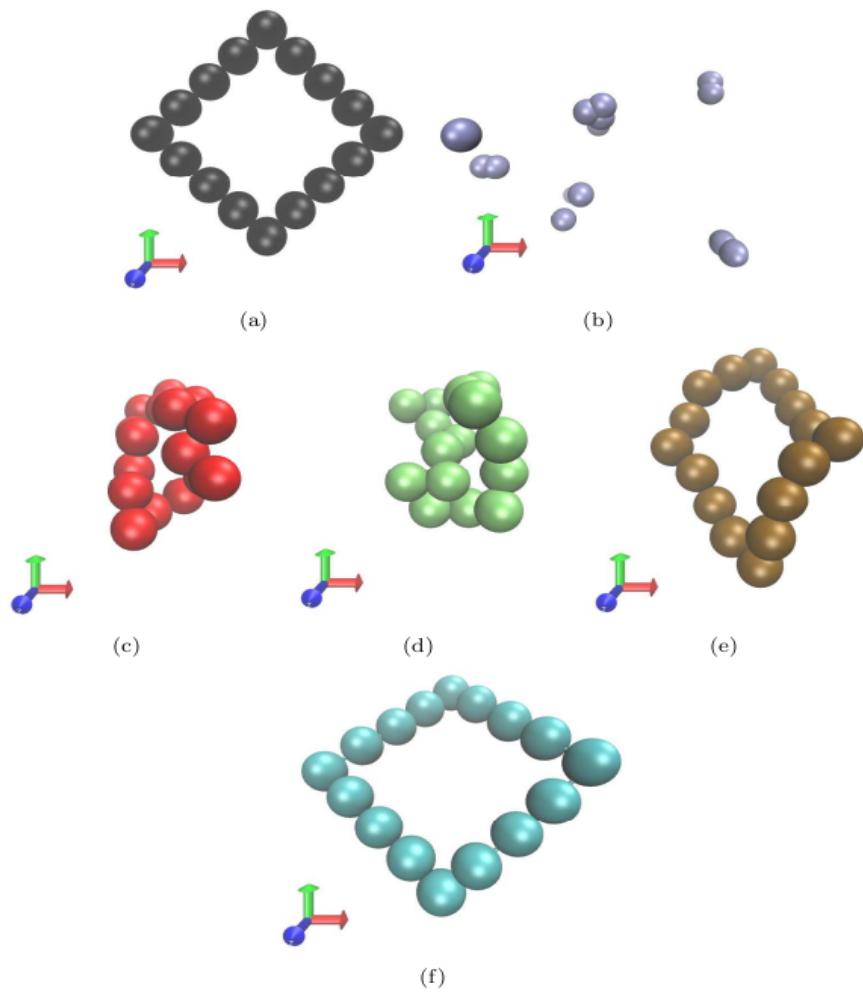


# Cross-Shaped Agglomerate





# Square-shaped Agglomerate Simulation Results



(a) initial  
structure

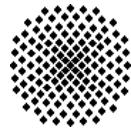
(b) LJ model

(c) SB model

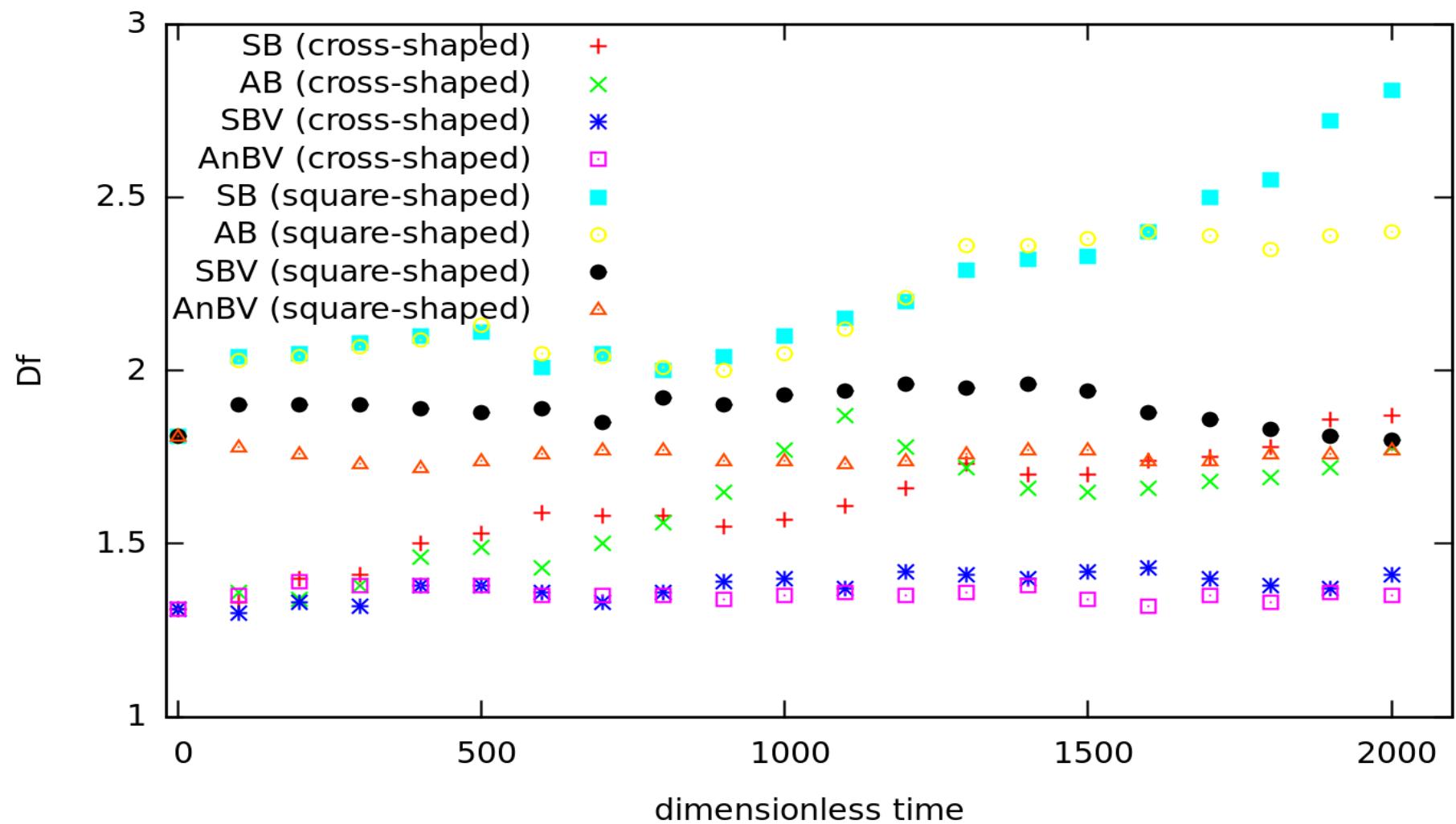
(d) AB model

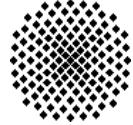
(e) SBV model

(f) AnBV  
model

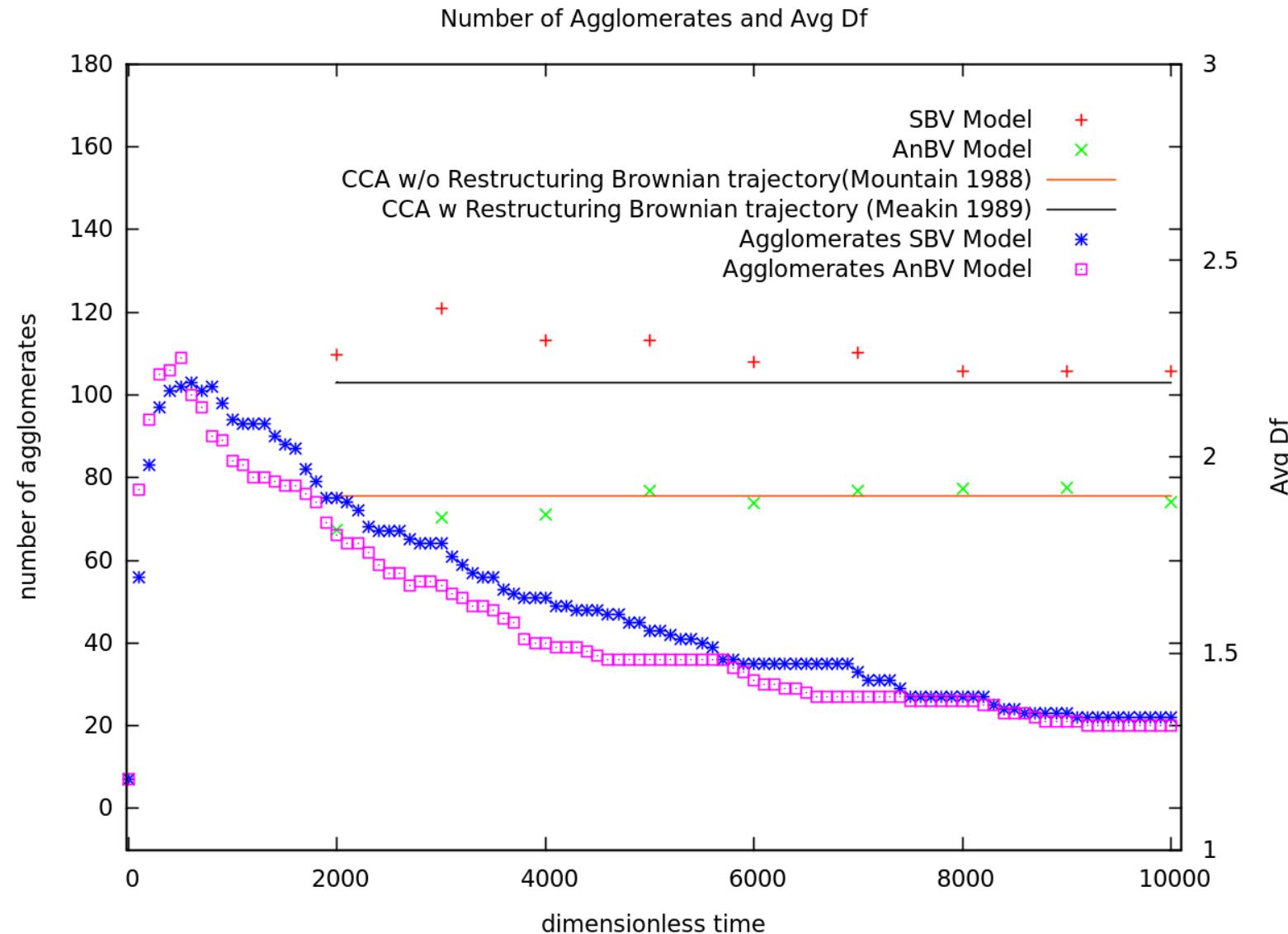


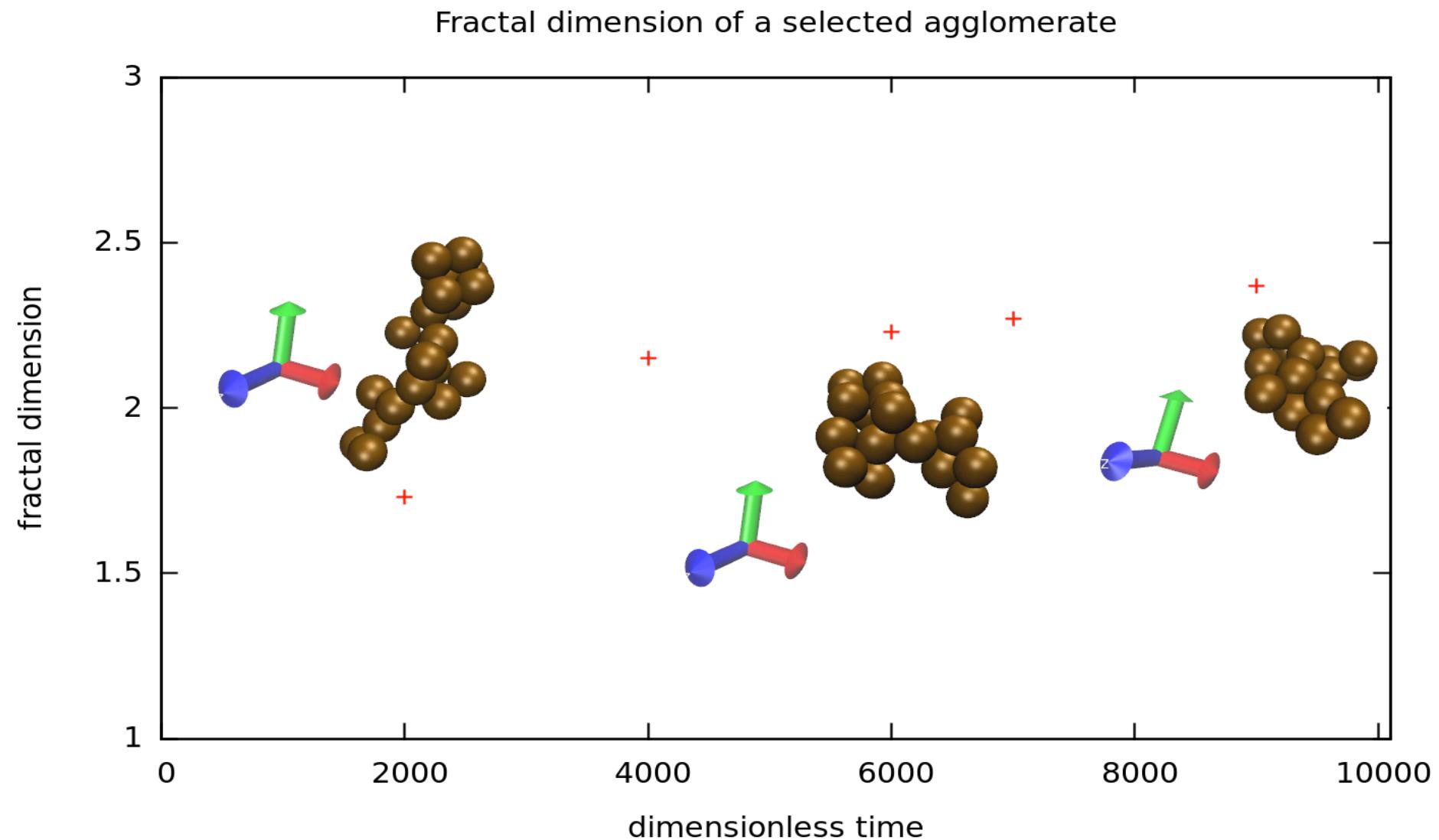
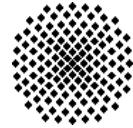
# Evolution of fractal dimension

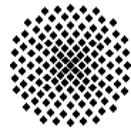




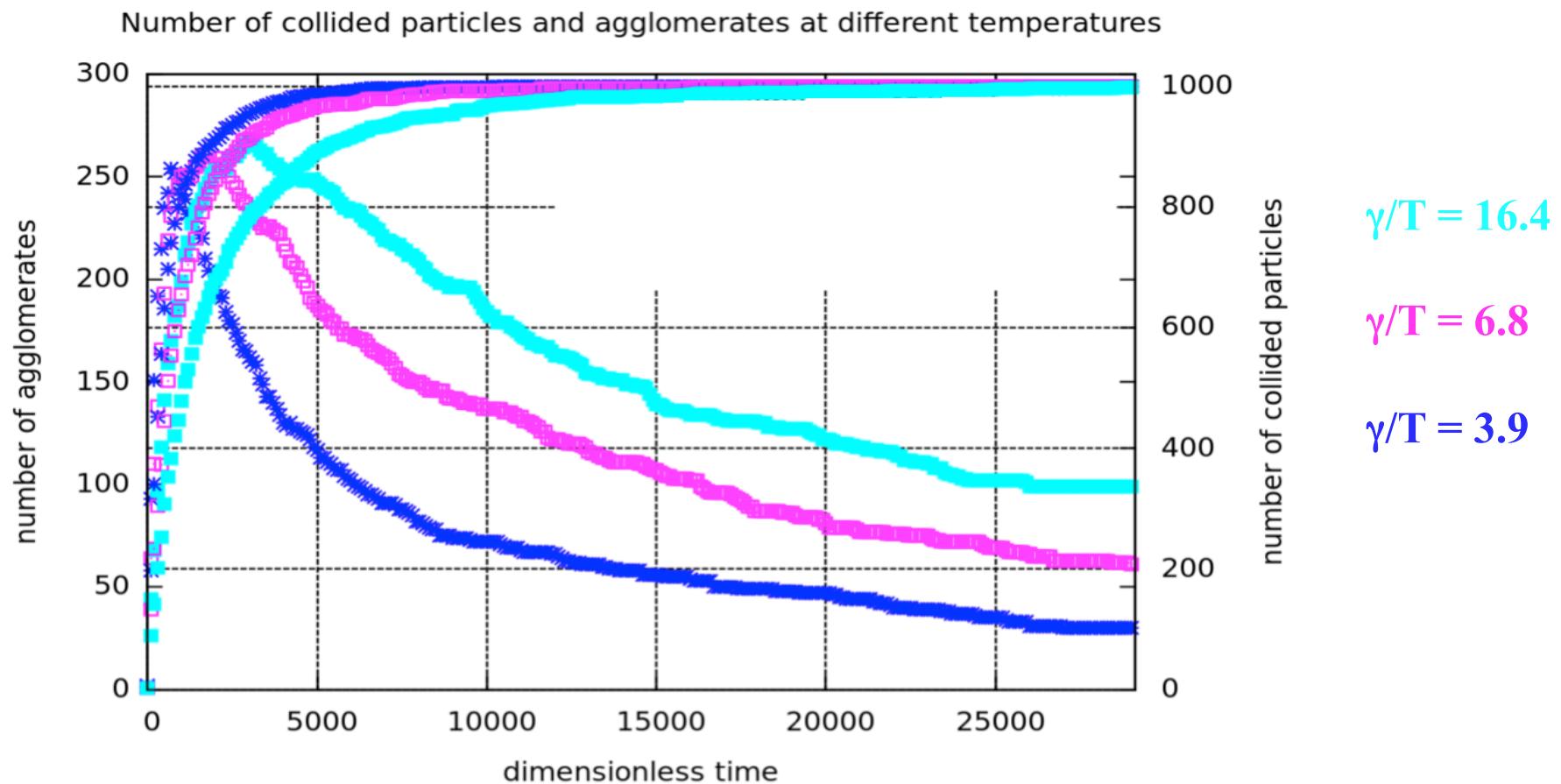
# Particle Agglomeration (Case 3a)

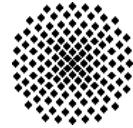






# Effect of viscosity





# What is this again?

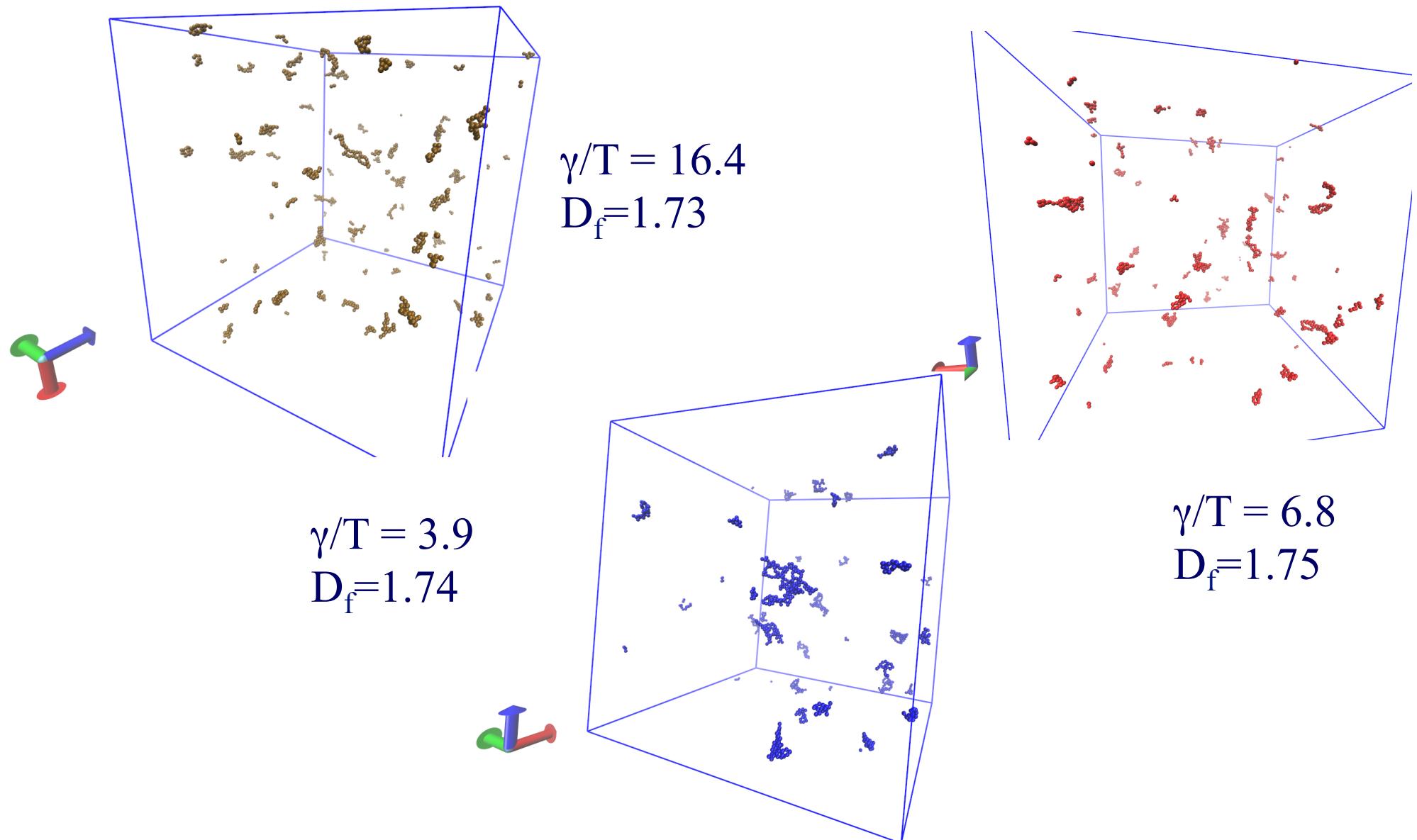
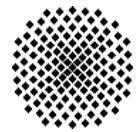
Normalized time/ avg.Df	16.4	6.8	3.9
10000	-	-	1.82
20000	-	1.77	1.77
47000	1.72	-	1.745
52000	-	-	1.73

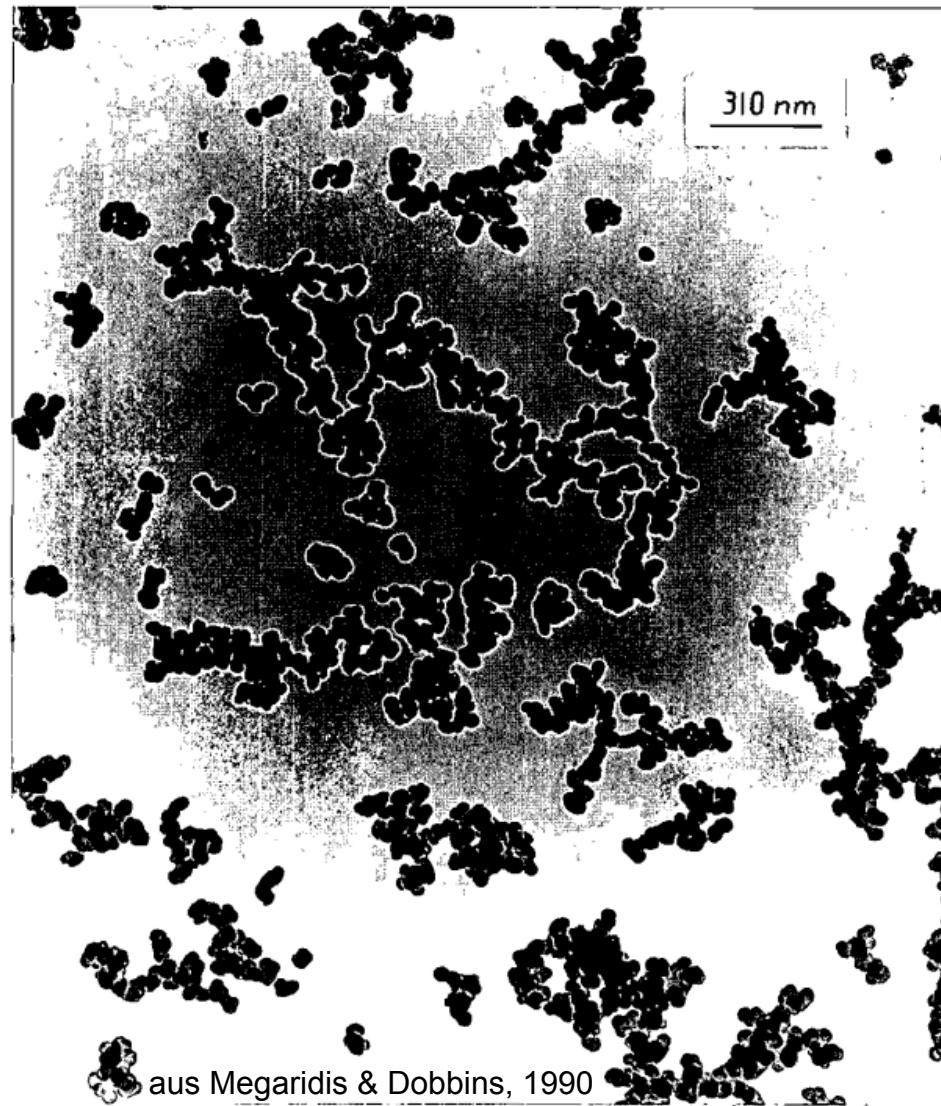
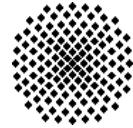
CCA (Brownian  
Trajectory)

Meakin 1983

Df=1.75 ± 0.05

CCA (Brownian  
Trajectory) w/o  
Reconstruction  
Kempf 1999  
Df=1.8

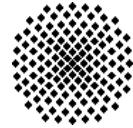




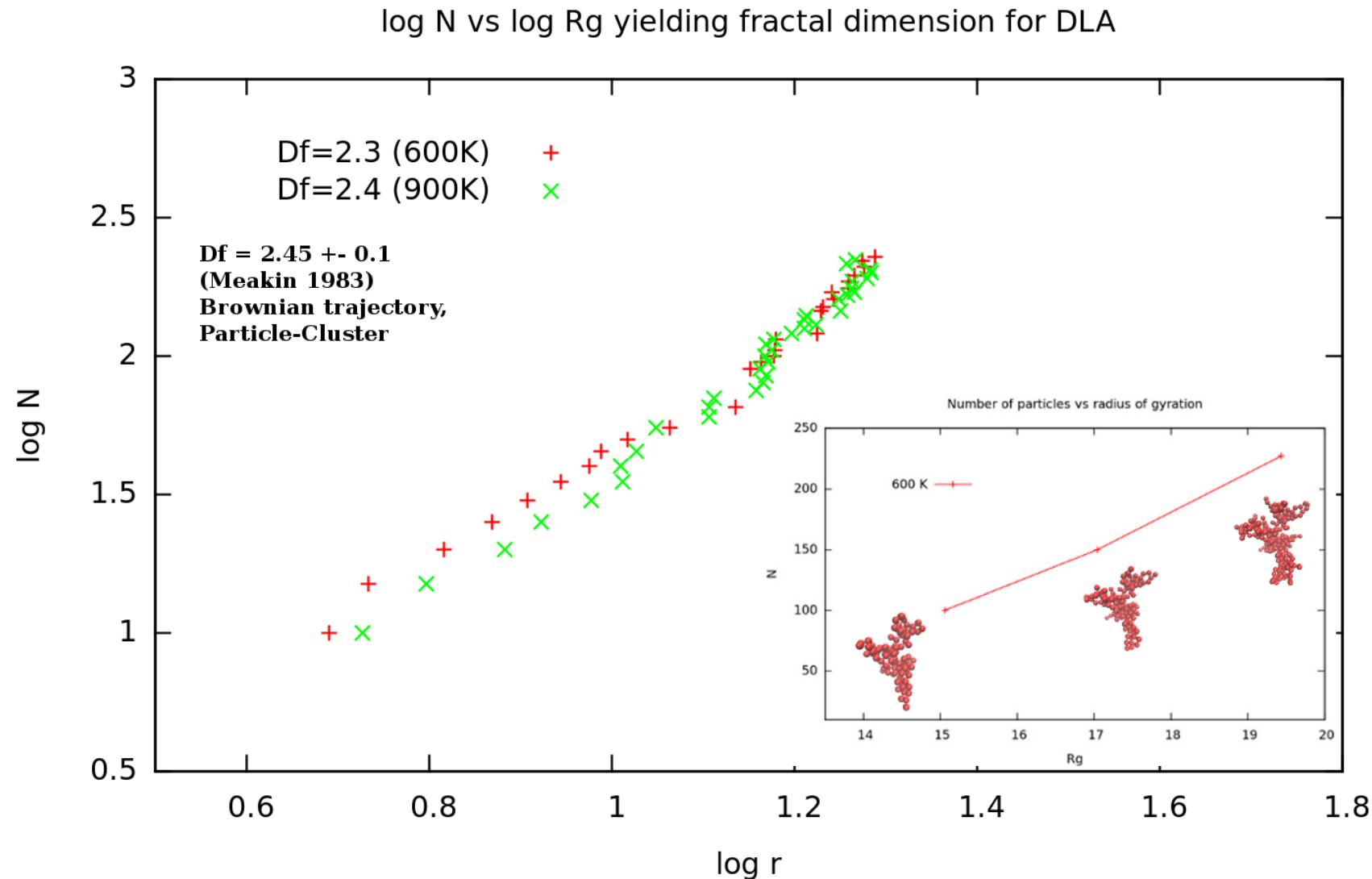
Electron micrograph of soot aggregates extracted from a co-annular ethylene diffusion flame.  
Position:  $z = 30\text{mm}$  &  $r = 2.1\text{mm}$ .

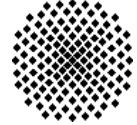
$$D_f = 1.74 \pm 0.06 \quad (@ z=15 \text{ mm}, r=3.7 \text{ mm})$$

$$D_f = 1.62 \pm 0.04 \quad (@ z=15 \text{ mm}, r=3.1 \text{ mm})$$



# DLA Simulation Results





## Conclusions

- **ESPResSo can be used for studies beyond molecular dynamics**
- **New contact models needed to be implemented**
- **“Rigid body motion” realized by virtual particles**
- **Aggregates resemble “real life” soot clusters**

## Future Work

- **Statistics for modelling of  $D_f$  and  $\beta$**
- **Interaction with flow field**